

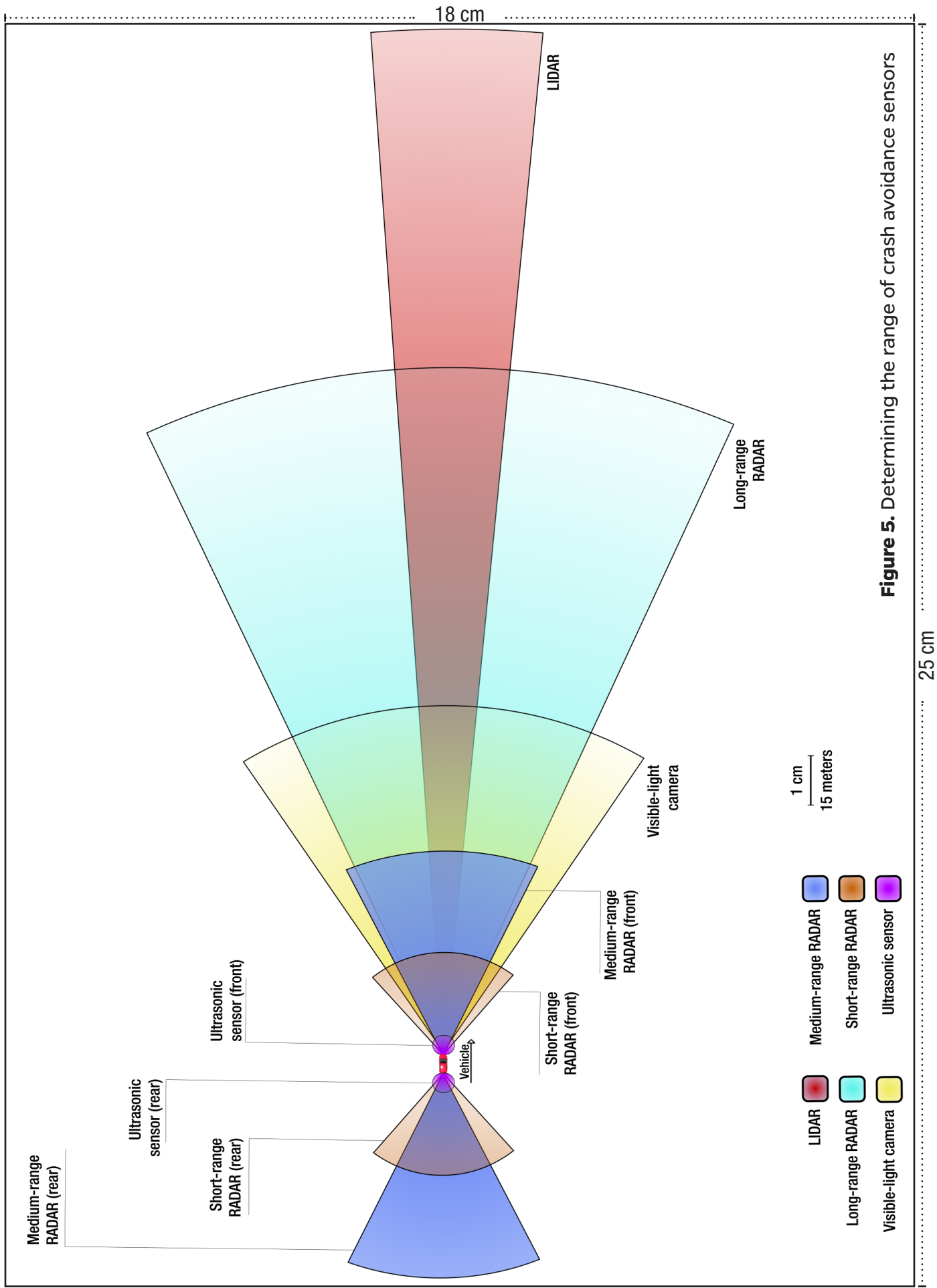


Figure 5. Determining the range of crash avoidance sensors